
Neoliberalism and local consistency

Tomáš Nagy

Jagiellonian University

joint work with Michael Pinsker

AAA 105, Prague, 1st June 2024

Views and opinions expressed do not reflect necessarily those of the author or of any other human being, dead or alive – in particular not of the co-author.

No individual or organisation can be held responsible for them.

Infinite structures

\mathbb{B} *homogeneous* if every orbit under $\text{Aut}(\mathbb{B})$ determined by relations

Example: $(\mathbb{Q}; <, =)$: $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

Infinite structures

\mathbb{B} *homogeneous* if every orbit under $\text{Aut}(\mathbb{B})$ determined by relations

Example: $(\mathbb{Q}; <, =)$: $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

\mathbb{B} *finitely bounded* if every description works

unless one of finitely many conditions (bounds) is satisfied

Infinite structures

\mathbb{B} *homogeneous* if every orbit under $\text{Aut}(\mathbb{B})$ determined by relations

Example: $(\mathbb{Q}; <, =)$: $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

\mathbb{B} *finitely bounded* if every description works

unless one of finitely many conditions (bounds) is satisfied

“No surprises in the eternity.” \Rightarrow seems to be what we desire

Infinite structures

\mathbb{B} *homogeneous* if every orbit under $\text{Aut}(\mathbb{B})$ determined by relations

Example: $(\mathbb{Q}; <, =)$: $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

\mathbb{B} *finitely bounded* if every description works

unless one of finitely many conditions (bounds) is satisfied

“No surprises in the eternity.” \Rightarrow seems to be what we desire

Example: $(\mathbb{Q}; <)$: $<$ irreflexive (forbids $x < x$), transitive (forbids $x < y < z$ without relations between x, z or with $x = z$), total (forbids x, y without relations)

Infinite structures

\mathbb{B} *homogeneous* if every orbit under $\text{Aut}(\mathbb{B})$ determined by relations

Example: $(\mathbb{Q}; <, =)$: $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

\mathbb{B} *finitely bounded* if every description works

unless one of finitely many conditions (bounds) is satisfied

“No surprises in the eternity.” \Rightarrow seems to be what we desire

Example: $(\mathbb{Q}; <)$: $<$ irreflexive (forbids $x < x$), transitive (forbids $x < y < z$ without relations between x, z or with $x = z$), total (forbids x, y without relations)

\mathbb{B} has *finite duality* if every *incomplete* description gives union of orbits unless one of finitely many conditions (*homomorphic* bounds) satisfied

Infinite structures

\mathbb{B} *homogeneous* if every orbit under $\text{Aut}(\mathbb{B})$ determined by relations

Example: $(\mathbb{Q}; <, =)$: $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

\mathbb{B} *finitely bounded* if every description works

unless one of finitely many conditions (bounds) is satisfied

“No surprises in the eternity.” \Rightarrow seems to be what we desire

Example: $(\mathbb{Q}; <)$: $<$ irreflexive (forbids $x < x$), transitive (forbids $x < y < z$ without relations between x, z or with $x = z$), total (forbids x, y without relations)

\mathbb{B} has *finite duality* if every *incomplete* description gives union of orbits unless one of finitely many conditions (*homomorphic* bounds) satisfied

“No surprises in the eternity even without full self-knowledge.”

\Rightarrow what we actually desire

Infinite structures

\mathbb{B} *homogeneous* if every orbit under $\text{Aut}(\mathbb{B})$ determined by relations

Example: $(\mathbb{Q}; <, =)$: $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

\mathbb{B} *finitely bounded* if every description works

unless one of finitely many conditions (bounds) is satisfied

“No surprises in the eternity.” \Rightarrow seems to be what we desire

Example: $(\mathbb{Q}; <)$: $<$ irreflexive (forbids $x < x$), transitive (forbids $x < y < z$ without relations between x, z or with $x = z$), total (forbids x, y without relations)

\mathbb{B} has *finite duality* if every *incomplete* description gives union of orbits unless one of finitely many conditions (*homomorphic* bounds) satisfied

“No surprises in the eternity even without full self-knowledge.”

\Rightarrow what we actually desire

Example: $(\mathbb{Q}; <)$ does NOT have finite duality:

all cycles forbidden $x_1 < x_2 < \dots < x_n < x_1$.

the universal homogeneous triangle-free graph has finite duality

Infinite-domain CSPs

\mathbb{B} - finitely bounded, homogeneous

\mathbb{A} - first-order definable in \mathbb{B}

CSP(\mathbb{A}):

Input: $\Phi = \phi_1 \wedge \dots \wedge \phi_k$ - conjunction of atomic formulas over the signature of \mathbb{A}

Question: Φ satisfiable?

\mathbb{B} - finitely bounded, homogeneous

\mathbb{A} - first-order definable in \mathbb{B}

CSP(\mathbb{A}):

Input: $\Phi = \phi_1 \wedge \dots \wedge \phi_k$ - conjunction of atomic formulas over the signature of \mathbb{A}

Question: Φ satisfiable?

Finite formulation:

maxarity(\mathbb{B}) = k , τ - signature of \mathbb{B}

Given:

- "values": O_1, \dots, O_m - k -orbits under $\text{Aut}(\mathbb{B})$,
- "constraints": constraints given by Φ (quantifier-free τ -formulas) + $\{F_1, \dots, F_n\}$ - finite forbidden τ -structures (bounds)

Want: assign to every k -tuple of free variables of Φ an orbit O_i s.t. no F_i embeds to the resulting structure and s.t. Φ is satisfied

\mathbb{B} is *liberal* if its relations correspond to orbits of pairs
and it does not have bounds of size 3 – 6

“If you are not free, you at least do not notice it.”

\mathbb{B} is *liberal* if its relations correspond to orbits of pairs and it does not have bounds of size 3 – 6

“If you are not free, you at least do not notice it.”

$k \geq 2$, \mathbb{B} is *k-neoliberal* if

- it is homogeneous and its relations correspond to orbits of k -tuples, and
 - \rightsquigarrow every orbit determined by k -ary relations
 - *clear and concise regulations*

\mathbb{B} is *liberal* if its relations correspond to orbits of pairs and it does not have bounds of size $3 - 6$

“If you are not free, you at least do not notice it.”

$k \geq 2$, \mathbb{B} is *k-neoliberal* if

- it is homogeneous and its relations correspond to orbits of k -tuples, and
 - \rightsquigarrow every orbit determined by k -ary relations
 - *clear and concise regulations*
- it has only one orbit of injective $(k - 1)$ -tuples, and
 - *free market – money can be transported between orbits by automorphisms without restrictions*

\mathbb{B} is *liberal* if its relations correspond to orbits of pairs and it does not have bounds of size 3 – 6

“If you are not free, you at least do not notice it.”

$k \geq 2$, \mathbb{B} is *k-neoliberal* if

- it is homogeneous and its relations correspond to orbits of k -tuples, and
 - \rightsquigarrow every orbit determined by k -ary relations
 - *clear and concise regulations*
- it has only one orbit of injective $(k - 1)$ -tuples, and
 - *free market – money can be transported between orbits by automorphisms without restrictions*
- for any injective orbit O of k -tuples, any injective $(k - 1)$ -tuple can be extended to a tuple in O in at least two ways
 - *it is easy to divert money and avoid taxes*

\mathbb{B} is *liberal* if its relations correspond to orbits of pairs and it does not have bounds of size 3 – 6

“If you are not free, you at least do not notice it.”

$k \geq 2$, \mathbb{B} is *k-neoliberal* if

- it is homogeneous and its relations correspond to orbits of k -tuples, and
 - \rightsquigarrow every orbit determined by k -ary relations
 - *clear and concise regulations*
- it has only one orbit of injective $(k - 1)$ -tuples, and
 - *free market – money can be transported between orbits by automorphisms without restrictions*
- for any injective orbit O of k -tuples, any injective $(k - 1)$ -tuple can be extended to a tuple in O in at least two ways
 - *it is easy to divert money and avoid taxes*

liberal \Rightarrow 2-neoliberal

Examples:

- $(\mathbb{Q}; <, =)$ is 2-neoliberal but not liberal
 - orbits determined by $<, =$,
 - any $a \in \mathbb{Q}$ can be moved by an automorphism to any other $b \in \mathbb{Q}$
 \Rightarrow one orbit of elements,
 - for any $a \in \mathbb{Q}$, there exist $b \neq c \in \mathbb{Q}$ with $a < b, a < c$,
 - transitivity enforced by a bound of size 3 \Rightarrow not liberal.

Examples:

- $(\mathbb{Q}; <, =)$ is 2-neoliberal but not liberal
 - orbits determined by $<, =$,
 - any $a \in \mathbb{Q}$ can be moved by an automorphism to any other $b \in \mathbb{Q}$
 \Rightarrow one orbit of elements,
 - for any $a \in \mathbb{Q}$, there exist $b \neq c \in \mathbb{Q}$ with $a < b, a < c$,
 - transitivity enforced by a bound of size 3 \Rightarrow not liberal.
- graph \mathbb{G} consisting of infinitely many isolated edges is NOT 2-neoliberal
 - for any $a \in G$, there is a unique b connected by an edge to a
 - \Rightarrow impossible to divert money

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of CSP(\mathbb{A})

How to solve CSP(\mathbb{A})?

Local consistency: Derive information locally,
constraints have to agree on small subsets of variables

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of $\text{CSP}(\mathbb{A})$

How to solve $\text{CSP}(\mathbb{A})$?

Local consistency: Derive information locally,
constraints have to agree on small subsets of variables

“Example”: Computing the transitive closure of a binary relation R .

$\phi_i : R(x, y), \phi_j : R(y, z) \Rightarrow \text{add } \phi := R(x, z) \text{ to } \Phi$

\rightsquigarrow looking on *triples*, deriving information about *pairs* of variables

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of $\text{CSP}(\mathbb{A})$

How to solve $\text{CSP}(\mathbb{A})$?

Local consistency: Derive information locally,
constraints have to agree on small subsets of variables

“Example”: Computing the transitive closure of a binary relation R .

$\phi_i : R(x, y), \phi_j : R(y, z) \Rightarrow$ add $\phi := R(x, z)$ to Φ

\leadsto looking on *triples*, deriving information about *pairs* of variables

$R^{\mathbb{A}}$ irreflexive, transitive and we derive $R(x, x) \Rightarrow \Phi$ not satisfiable.

\Rightarrow sometimes, local consistency *solves* $\text{CSP}(\mathbb{A})$

Local consistency, 2/4

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of CSP(\mathbb{A}), variable set \mathcal{V}

scope S of ϕ_i : all variables of ϕ_i

projection of ϕ_i to $X \subseteq S$: $\exists x_1 \dots x_\ell \phi_i$, where $S \setminus X = \{x_1, \dots, \dots x_\ell\}$

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of $\text{CSP}(\mathbb{A})$, variable set \mathcal{V}

scope S of ϕ_i : all variables of ϕ_i

projection of ϕ_i to $X \subseteq S$: $\exists x_1 \dots x_\ell \phi_i$, where $S \setminus X = \{x_1, \dots, \dots x_\ell\}$

Φ (m, n) -*minimal* if

- for every set of $\leq n$ variables from \mathcal{V} , some ϕ_i contains all these variables in its scope, and
- for every set V of $\leq m$ variables from \mathcal{V} and for all ϕ_i, ϕ_j containing all variables from V in their scopes, the projections to V agree.

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of CSP(\mathbb{A}), variable set \mathcal{V}

scope S of ϕ_i : all variables of ϕ_i

projection of ϕ_i to $X \subseteq S$: $\exists x_1 \dots x_\ell \phi_i$, where $S \setminus X = \{x_1, \dots, x_\ell\}$

Φ (m, n) -minimal if

- for every set of $\leq n$ variables from \mathcal{V} , some ϕ_i contains all these variables in its scope, and
- for every set V of $\leq m$ variables from \mathcal{V} and for all ϕ_i, ϕ_j containing all variables from V in their scopes, the projections to V agree.

\rightsquigarrow possible to compute an (m, n) -minimal “instance” from Φ effectively, we do not lose solutions

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of CSP(\mathbb{A}), variable set \mathcal{V}

scope S of ϕ_i : all variables of ϕ_i

projection of ϕ_i to $X \subseteq S$: $\exists x_1 \dots x_\ell \phi_i$, where $S \setminus X = \{x_1, \dots, x_\ell\}$

Φ (m, n) -*minimal* if

- for every set of $\leq n$ variables from \mathcal{V} , some ϕ_i contains all these variables in its scope, and
- for every set V of $\leq m$ variables from \mathcal{V} and for all ϕ_i, ϕ_j containing all variables from V in their scopes, the projections to V agree.

\rightsquigarrow possible to compute an (m, n) -minimal “instance” from Φ effectively, we do not lose solutions

Φ is *non-trivial* if every ϕ_i satisfiable

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of $\text{CSP}(\mathbb{A})$, variable set \mathcal{V}

scope S of ϕ_i : all variables of ϕ_i

projection of ϕ_i to $X \subseteq S$: $\exists x_1 \dots x_\ell \phi_i$, where $S \setminus X = \{x_1, \dots, \dots x_\ell\}$

Φ (m, n) -minimal if

- for every set of $\leq n$ variables from \mathcal{V} , some ϕ_i contains all these variables in its scope, and
- for every set V of $\leq m$ variables from \mathcal{V} and for all ϕ_i, ϕ_j containing all variables from V in their scopes, the projections to V agree.

\leadsto possible to compute an (m, n) -minimal “instance” from Φ effectively, we do not lose solutions

Φ is *non-trivial* if every ϕ_i satisfiable

\mathbb{A} has (*relational*) *width* (m, n) if every non-trivial (m, n) -minimal instance satisfiable

\leadsto local consistency solves $\text{CSP}(\mathbb{A})$

Examples:

- $(\mathbb{Q}; =, <)$ has width $(2, 3)$
 - Idea: ensure that the transitive closure of $<$ is irreflexive.
 - looking on *triples* of variables, comparing projections on *pairs*

Examples:

- $(\mathbb{Q}; =, <)$ has width $(2, 3)$
 - Idea: ensure that the transitive closure of $<$ is irreflexive.
 - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$
does not have bounded width
 - linear equations cannot be solved by deriving local information

Examples:

- $(\mathbb{Q}; =, <)$ has width $(2, 3)$
 - Idea: ensure that the transitive closure of $<$ is irreflexive.
 - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$
does not have bounded width
 - linear equations cannot be solved by deriving local information

Local consistency: only small, local and necessary changes,
does not waste resources \Rightarrow *conservative*

Examples:

- $(\mathbb{Q}; =, <)$ has width $(2, 3)$
 - Idea: ensure that the transitive closure of $<$ is irreflexive.
 - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$
does not have bounded width
 - linear equations cannot be solved by deriving local information

Local consistency: only small, local and necessary changes,
does not waste resources \Rightarrow *conservative*

Linear equations: costly, ineffective (Gaussian elimination),
constantly invents something new that never works out
(more effective algorithms) \Rightarrow *socialist*

Examples:

- $(\mathbb{Q}; =, <)$ has width $(2, 3)$
 - Idea: ensure that the transitive closure of $<$ is irreflexive.
 - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$
does not have bounded width
 - linear equations cannot be solved by deriving local information

Local consistency: only small, local and necessary changes,
does not waste resources \Rightarrow *conservative*

Linear equations: costly, ineffective (Gaussian elimination),
constantly invents something new that never works out
(more effective algorithms) \Rightarrow *socialist*

Fun fact: Finite-domain CSP solved by a combination
of local consistency and linear equations (Bulatov, Zhuk, 2017)

Examples:

- $(\mathbb{Q}; =, <)$ has width $(2, 3)$
 - Idea: ensure that the transitive closure of $<$ is irreflexive.
 - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$
does not have bounded width
 - linear equations cannot be solved by deriving local information

Local consistency: only small, local and necessary changes,
does not waste resources \Rightarrow *conservative*

Linear equations: costly, ineffective (Gaussian elimination),
constantly invents something new that never works out
(more effective algorithms) \Rightarrow *socialist*

Fun fact: Finite-domain CSP solved by a combination
of local consistency and linear equations (Bulatov, Zhuk, 2017)
 \Rightarrow Grand coalition (“building bridges”)

\mathbb{A} finite $\Rightarrow \mathbb{A}$ has width $(m, n) \Leftrightarrow$ it has width $(2, 3)$

Collapse (Barto, 2016)

bounded width has an algebraic characterization

\mathbb{A} finite $\Rightarrow \mathbb{A}$ has width $(m, n) \Leftrightarrow$ it has width $(2, 3)$

Collapse (Barto, 2016)

bounded width has an algebraic characterization

\mathbb{A} infinite \Rightarrow no uniform bound, no algebraic characterization

\mathbb{A} finite $\Rightarrow \mathbb{A}$ has width $(m, n) \Leftrightarrow$ it has width $(2, 3)$

Collapse (Barto, 2016)

bounded width has an algebraic characterization

\mathbb{A} infinite \Rightarrow no uniform bound, no algebraic characterization

Question: \mathbb{A} fo-definable in a finitely bounded homogeneous \mathbb{B} ,
 \mathbb{A} has bounded width.

Does there exist a bound on the width of \mathbb{A} depending only on \mathbb{B} ?

\mathbb{A} fo-definable in \mathbb{B}

k – *maxarity*(\mathbb{B}), ℓ – size of the biggest bound

Does there exist a bound on the width of \mathbb{A} depending only on \mathbb{B} ?

Assume: \mathbb{A} has a relation for every orbit of k -tuples under $\text{Aut}(\mathbb{B})$.

What is the minimal possible width of \mathbb{A} ?

\mathbb{A} fo-definable in \mathbb{B}

k – *maxarity*(\mathbb{B}), ℓ – size of the biggest bound

Does there exist a bound on the width of \mathbb{A} depending only on \mathbb{B} ?

Assume: \mathbb{A} has a relation for every orbit of k -tuples under $\text{Aut}(\mathbb{B})$.

What is the minimal possible width of \mathbb{A} ?

- Need $(k, \text{something})$ to check that no tuple lies in two orbits.

\mathbb{A} fo-definable in \mathbb{B}

k – *maxarity*(\mathbb{B}), ℓ – size of the biggest bound

Does there exist a bound on the width of \mathbb{A} depending only on \mathbb{B} ?

Assume: \mathbb{A} has a relation for every orbit of k -tuples under $\text{Aut}(\mathbb{B})$.

What is the minimal possible width of \mathbb{A} ?

- Need $(k, \text{something})$ to check that no tuple lies in two orbits.
- Need $(\text{something}, \ell)$ to get all constraints given by bounds.

\mathbb{A} fo-definable in \mathbb{B}

k – *maxarity*(\mathbb{B}), ℓ – size of the biggest bound

Does there exist a bound on the width of \mathbb{A} depending only on \mathbb{B} ?

Assume: \mathbb{A} has a relation for every orbit of k -tuples under $\text{Aut}(\mathbb{B})$.

What is the minimal possible width of \mathbb{A} ?

- Need $(k, \text{something})$ to check that no tuple lies in two orbits.
- Need $(\text{something}, \ell)$ to get all constraints given by bounds.
- If = among relations of $\mathbb{A} \Rightarrow$ need $(k, k + 1)$ to exclude

$$(x_1, \dots, x_k) \in O, (x_1, \dots, x_{k-1}, y) \in P, x_k = y$$

for $O \neq P$

$\leadsto \mathbb{A}$ has relational width at least $(k, \max(k + 1, \ell))$.

\mathbb{A} fo-definable in \mathbb{B}

$k - \text{maxarity}(\mathbb{B}), \ell - \text{size of the biggest bound}$

Does there exist a bound on the width of \mathbb{A} depending only on \mathbb{B} ?

Know: natural lower bound: $(k, \max(k + 1, \ell))$

\mathbb{A} fo-definable in \mathbb{B}

$k - \text{maxarity}(\mathbb{B}), \ell - \text{size of the biggest bound}$

Does there exist a bound on the width of \mathbb{A} depending only on \mathbb{B} ?

Know: natural lower bound: $(k, \max(k + 1, \ell))$

\mathbb{A} finite with n elements $\Rightarrow \mathbb{A}$ fo-definable from

$\mathbb{B} := (\{1, \dots, n\}, \{1\}, \dots, \{n\})$

Collapse $\rightsquigarrow \mathbb{A}$ has relational width $(2, 3)$.

\mathbb{A} fo-definable in \mathbb{B}

$k - \text{maxarity}(\mathbb{B}), \ell - \text{size of the biggest bound}$

Does there exist a bound on the width of \mathbb{A} depending only on \mathbb{B} ?

Know: natural lower bound: $(k, \max(k + 1, \ell))$

\mathbb{A} finite with n elements $\Rightarrow \mathbb{A}$ fo-definable from

$\mathbb{B} := (\{1, \dots, n\}, \{1\}, \dots, \{n\})$

Collapse $\rightsquigarrow \mathbb{A}$ has relational width $(2, 3)$.

Idea: $k = 1, \ell = 2$ (forbid $a \in \{i\} \cap \{j\}, a, b \in \{i\}$)

\Rightarrow Natural guess for upper bound on the width of \mathbb{A} : $(2k, \max(3k, \ell))$

Is this true also for infinite \mathbb{A} ???

\mathbb{A} fo-definable in \mathbb{B}

$k - \text{maxarity}(\mathbb{B}), \ell - \text{size of the biggest bound}$

Does there exist a bound on the width of \mathbb{A} depending only on \mathbb{B} ?

Know: natural lower bound: $(k, \max(k + 1, \ell))$

\mathbb{A} finite with n elements $\Rightarrow \mathbb{A}$ fo-definable from

$\mathbb{B} := (\{1, \dots, n\}, \{1\}, \dots, \{n\})$

Collapse $\rightsquigarrow \mathbb{A}$ has relational width $(2, 3)$.

Idea: $k = 1, \ell = 2$ (forbid $a \in \{i\} \cap \{j\}, a, b \in \{i\}$)

\Rightarrow Natural guess for upper bound on the width of \mathbb{A} : $(2k, \max(3k, \ell))$

Is this true also for infinite \mathbb{A} ???

Often YES.

No counterexample known!

Strict width

$$m \geq 1$$

\mathbb{A} has *strict width* m if there exists $n \geq m$

s. t. for every (m, n) -minimal instance,
any *local solution* can be extended to a global one.

Strict width

$$m \geq 1$$

\mathbb{A} has *strict width* m if there exists $n \geq m$

s. t. for every (m, n) -minimal instance,
any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of $\text{CSP}(\mathbb{A})$ over variables \mathcal{V}

Want: for any $U \subseteq \mathcal{V}$, any assignment $f: U \rightarrow A$ satisfying projection
of every ϕ_i to U can be extended to a satisfying assignment for Φ .

$$m \geq 1$$

\mathbb{A} has *strict width* m if there exists $n \geq m$

s. t. for every (m, n) -minimal instance,
any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of $\text{CSP}(\mathbb{A})$ over variables \mathcal{V}

Want: for any $U \subseteq \mathcal{V}$, any assignment $f: U \rightarrow A$ satisfying projection of every ϕ_i to U can be extended to a satisfying assignment for Φ .

\Rightarrow far-right (extreme local consistency, controls too much,
kills everybody who doesn't contribute to the intended global solution)

$$m \geq 1$$

\mathbb{A} has *strict width* m if there exists $n \geq m$

s. t. for every (m, n) -minimal instance,
any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of $\text{CSP}(\mathbb{A})$ over variables \mathcal{V}

Want: for any $U \subseteq \mathcal{V}$, any assignment $f: U \rightarrow A$ satisfying projection of every ϕ_i to U can be extended to a satisfying assignment for Φ .

\Rightarrow far-right (extreme local consistency, controls too much,
kills everybody who doesn't contribute to the intended global solution)

Example: the universal triangle-free graph has strict width 2
(need $(2, 3)$ -minimality)

$$m \geq 1$$

\mathbb{A} has *strict width* m if there exists $n \geq m$

s. t. for every (m, n) -minimal instance,
any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of $\text{CSP}(\mathbb{A})$ over variables \mathcal{V}

Want: for any $U \subseteq \mathcal{V}$, any assignment $f: U \rightarrow A$ satisfying projection of every ϕ_i to U can be extended to a satisfying assignment for Φ .

\Rightarrow far-right (extreme local consistency, controls too much,
kills everybody who doesn't contribute to the intended global solution)

Example: the universal triangle-free graph has strict width 2
(need $(2, 3)$ -minimality)

Algebraic characterization: finite or infinite (ω -cat.) \mathbb{A}

has strict width $k \Leftrightarrow$ for every finite $F \subseteq A$,

\exists a $(k + 1)$ -ary *polymorphism* of \mathbb{A} which is a *near-unanimity* on F :

$$x \approx f(x, \dots, x) \approx f(y, x, \dots, x) \approx \dots \approx f(x, \dots, x, y)$$

$$m \geq 1$$

\mathbb{A} has *strict width* m if there exists $n \geq m$

s. t. for every (m, n) -minimal instance,
any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$ – instance of $\text{CSP}(\mathbb{A})$ over variables \mathcal{V}

Want: for any $U \subseteq \mathcal{V}$, any assignment $f: U \rightarrow A$ satisfying projection of every ϕ_i to U can be extended to a satisfying assignment for Φ .

\Rightarrow far-right (extreme local consistency, controls too much,
kills everybody who doesn't contribute to the intended global solution)

Example: the universal triangle-free graph has strict width 2
(need $(2, 3)$ -minimality)

Algebraic characterization: finite or infinite (ω -cat.) \mathbb{A}

has strict width $k \Leftrightarrow$ for every finite $F \subseteq A$,

\exists a $(k + 1)$ -ary *polymorphism* of \mathbb{A} which is a *near-unanimity* on F :

$$x \approx f(x, \dots, x) \approx f(y, x, \dots, x) \approx \dots \approx f(x, \dots, x, y)$$

No collapse even for finite \mathbb{A} !

A contribution to the progress of the human race

$k \geq 3$,

\mathbb{B} – k -neoliberal, has finite duality,

ℓ – size of the biggest bound for \mathbb{B}

\mathbb{A} – fo-definable in \mathbb{B} , has all relations of \mathbb{B}

Theorem. [N., Pinsker]

If \mathbb{A} has bounded strict width

$\Rightarrow \mathbb{A}$ has relational width $(k, \max(k + 1, \ell))$.

$k \geq 3$,

\mathbb{B} – k -neoliberal, has finite duality,

ℓ – size of the biggest bound for \mathbb{B}

\mathbb{A} – fo-definable in \mathbb{B} , has all relations of \mathbb{B}

Theorem. [N., Pinsker]

If \mathbb{A} has bounded strict width

$\Rightarrow \mathbb{A}$ has relational width $(k, \max(k + 1, \ell))$.

$\Rightarrow \mathbb{A}$ has as low relational width as possible

Idea: using the algebraic characterization of strict width,
show that certain “implications” $R(x_1, \dots, x_m) \Rightarrow S(y_1, \dots, y_n)$
not preserved by near-unanimity

$k \geq 3$,

\mathbb{B} – k -neoliberal, has finite duality,

ℓ – size of the biggest bound for \mathbb{B}

\mathbb{A} – fo-definable in \mathbb{B} , has all relations of \mathbb{B}

Theorem. [N., Pinsker]

If \mathbb{A} has bounded strict width

$\Rightarrow \mathbb{A}$ has relational width $(k, \max(k + 1, \ell))$.

$\Rightarrow \mathbb{A}$ has as low relational width as possible

Idea: using the algebraic characterization of strict width,
show that certain “implications” $R(x_1, \dots, x_m) \Rightarrow S(y_1, \dots, y_n)$
not preserved by near-unanimity

*“Neoliberalism implies that if a problem can be solved
by installing a fascist regime (strict width),
it can be solved in a much easier way and with less resources
using conservative policies (relational width).”*



Thank you for your attention!